# SeungJae (Jay) Baek

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#### **EDUCATION**

 University of California, Los Angeles (UCLA) **Electrical Engineering Major** 

#### **RELEVANT COURSEWORK**

Principles of Photonics · Electromagnetic Waves · Digital Signal Processing

· System Design · Principles of Semiconductor Device Design · Logic Design of Digital Systems

Analog Electronic Circuits · Microwave Circuits · Wireless Communication Links and Antennas

#### WORKING EXPERIENCE

- Ozcan Research Group at UCLA
  - HHMI Undergraduate Research Assistant Sperm Tracking with 2D Imaging Platform
  - Built a new set up for Raspberry Pi Camera sensors with Python and improved capturing speed for 0 sequential images to increase the efficiency of the device
  - Converted Auto-focus functions that previous lab researchers wrote from MATLAB to C++

#### PROJECTS

#### Activities Recognition for Walking, Jogging, and Squatting

- o Designed wireless-wearable sensors to identify and measure participant's activities
- Implemented C and Arduino so that IMUs can send data to a server via Wi-Fi using Linux kernel 0
- Developed MATLAB code to analyze data, to visualize, and to identify the participant's activities

#### Wireless Air Mouse at IEEE

- Implemented Arduino code so that a microcontroller can be used as a computer mouse with SPI, I2C, and UART communication between two MCUs using RF24 and IMU
- Built circuits for two MCUs with LEDs and switches for battery status and click functions respectively 0

### Circuit Design Project

- o Designed a circuit that removes 10kHz from a corrupted signal
- Developed a Band-reject filter with center frequency of 60Hz to satisfy given conditions
- Implemented a simulation with SPICE software and MATLAB
- NATCAR (Automatic Line-Following Racing Car) at IEEE
  - Implemented tests and built codes for motor, servo control, and PID controller with a microcontroller
  - Designed a line detection algorithm for line scan camera and invented a fast-stop mechanism for PID 0 controller

#### Vending Machine Design

- Built a sequential circuit for FSM consisted of multiple logic gates and two JK flip-flops rom high-level specification
- Implemented Verilog so that a simulation for correctness of codes can be done

#### Autonomous Arduino RC Car

- o Implemented Arduino code so that a RC car can autonomously drive itself using ultrasonic sensors
- Developed one ultrasonic sensor as a radar system with a servo so that it can rotate 180 degrees to monitor any obstacles and send the date (angle and distance) to a computer via serial port
- o Built a circuit to control a DC motor's direction and to monitor a battery's status

### **RELEVANT SKILLS**

- Familiarity with C, C#, C++, Python, Arduino IDE, Verilog, MATLAB, and SPICE tools
- Ability to utilize function generators, oscilloscopes, multimeters, and soldering
- Skilled at technical writing and using Microsoft Word, Excel, and PowerPoint
- Languages: Korean (Native), English (Fluent), and Japanese (Beginner)

## Spring 2015

#### Fall 2016 – Present

Fall 2015

Winter 2016

Fall 2016

Fall 2014

### Oct 2016 – Present